

Precision Harvesting System: A Promising Technology to Improve Harvestable Berry Yield and Quality



**WBPANS Annual Meeting
Dalhousie Agricultural Campus
November 22, 2013**

Objectives

- **Develop improved integrated harvesting management systems = coupling of mechanical, biological and environmental processes**
- **Increase the berry picking efficiency of blueberry harvester = LOWER cost of production**

Improved Integrated Harvesting System

- **Sensor Fusion System to Identify Sources of Error**
 - **Quantification of Multiple Fruit Losses during Harvesting**
 - **Impact of Relative Velocity and Different Header Forces on Fruit Picking Efficiency**
 - **Development of Bio-System Modeling for coupling of biological, environmental and mechanical processes**
 - **Design Analysis of Harvester Heads**
 - **Comparison of Different Harvester Heads**
 - **On-Line Computer Program for Precise Berry Harvesting**
- Recommendations**

Precision Agriculture Research Team



Background

Harvesting expense, shortage of labor and short season were the basis for mechanized harvester ¹

Research on the development of the mechanical harvester started in early 1950s, a viable mechanical harvester was not produced until the 1980s ²

Gray 1969 developed hollow reel raking mechanism to pick wild blueberries (Chisholm-Ryder Co.) ¹

¹Yarbrough, D. E, 1992. HortScience. 27:60.

² Dale et al., 1994. Hort. Review. 16:255-382.

³ Rhodes, R. B. 1961. Paper # NA61-206 (ASAE).

Background

- DBE harvester commercialized harvester in early 1980.
- Quantify losses from existing commercial blueberry harvester
- Factors responsible for picking efficiency and improve berry quality
- Develop integrated harvester to increase harvestable fruit yield and quality



Sites: Nova Scotia, New Brunswick, Maine

NS:

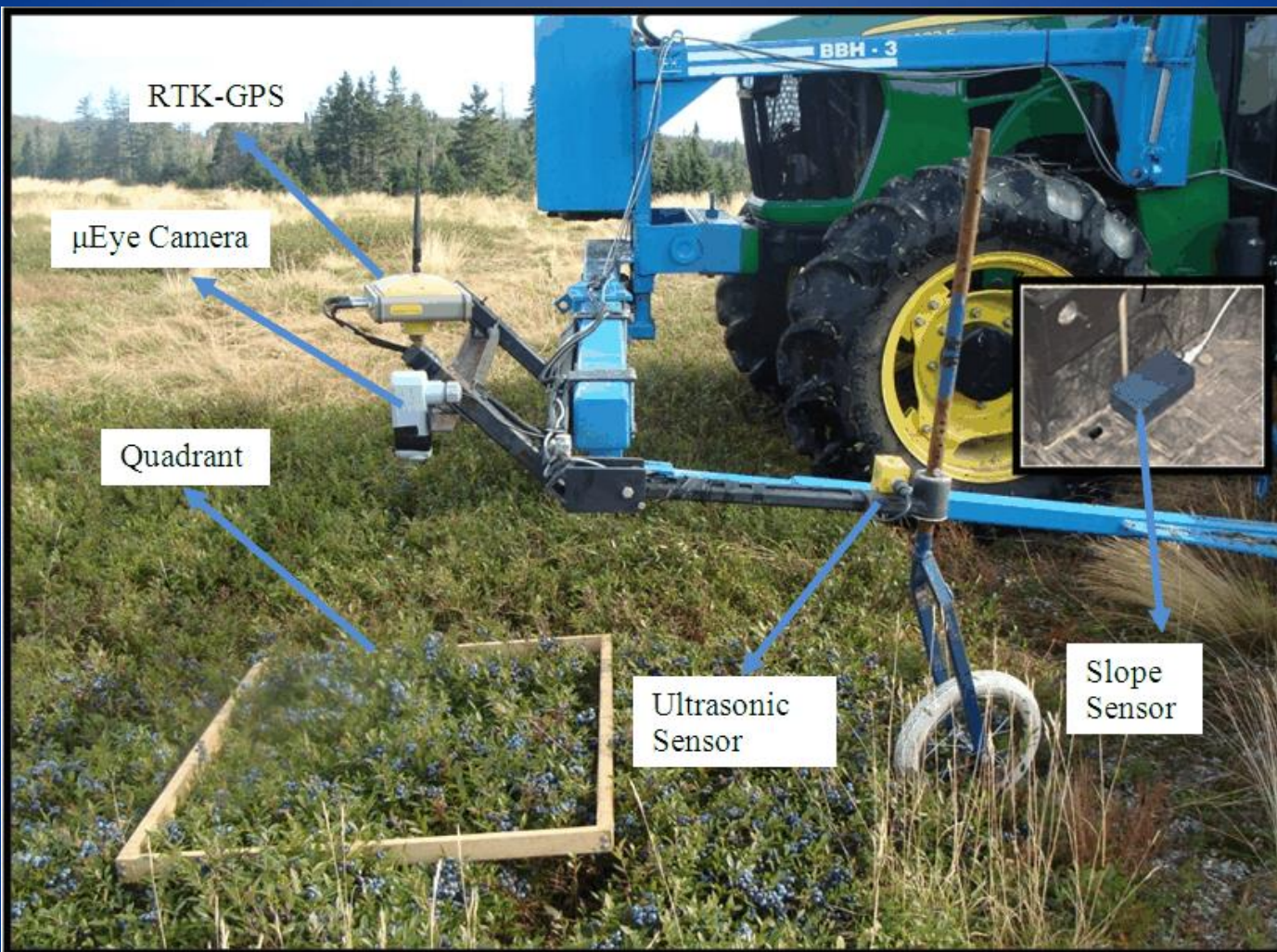
**Cooper Field
Small Scott Field
Frankweb Field
Hardwood Hill Field
Robie Glenn Field**

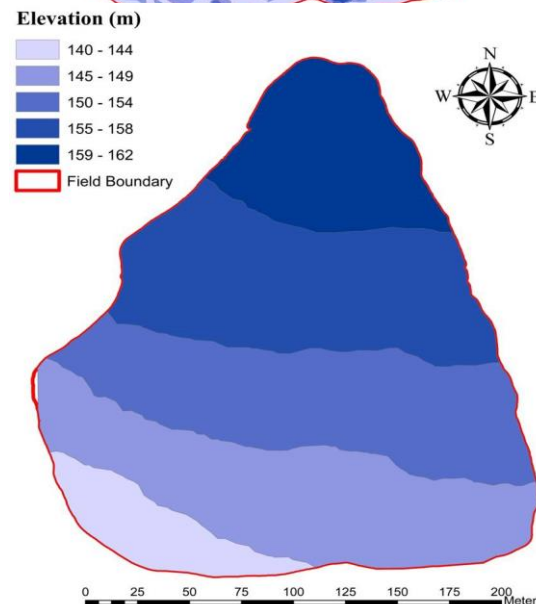
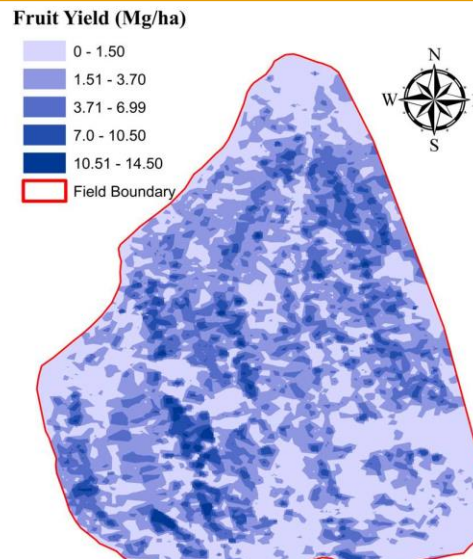
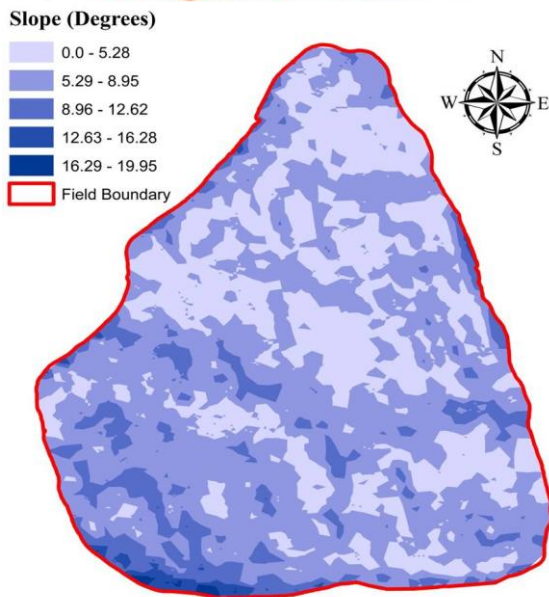
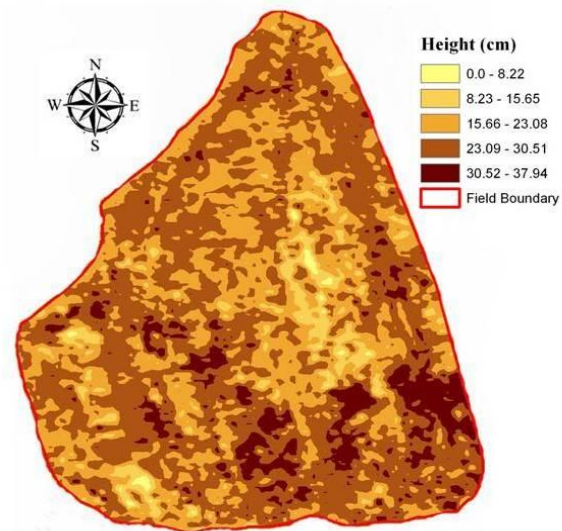
NB:

Tracadie

**Maine: Cherryfield
Wymans**

Sensor Fusion System





Quantification of Multiple Fruit Losses

Fruit Losses during harvesting:

- Total fruit yield
- Un-harvested berries on the plants
- Berries on the ground,
- Pre-harvest fruit loss
- Pan loss (Fruit collected in the pan behind head and
- Berries through blower



Mechanical Process: (Machine Parameters)

- Effect of different ground speed and head revolution on harvesting efficiency
- Effect of teeth length, angle and shape on berry picking efficiency
- Effect of wear and tear of harvester's parts on berry picking efficiency

Biological Process

Plant and Field Parameters:

Plant height

Plant density

Fruit zone,

Fruit size

Stem thickness

Weeds and Grasses

Soil conditions (texture, slope)



Environmental Processes

Seasonal and Climatic Effect (Time of Harvest):

Seasonal Effect:

Early season

Mid season

Late season

Climatic Effect:

Rainfall

Degree days

Humidity

Wind speed

Temperature



➤ Comparison of Different Harvester Heads

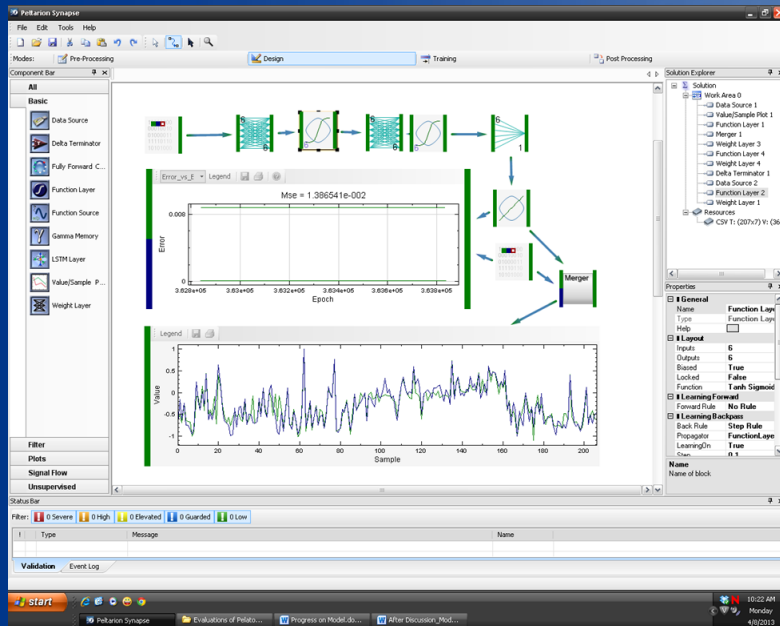
Harvester efficiency with 12 bars head vs. 16 bars head

➤ Design Analysis of Harvester Heads



Bio-System Modeling

Coupling of mechanical, biological and environmental processes



Operator Skill and Field Conditions:

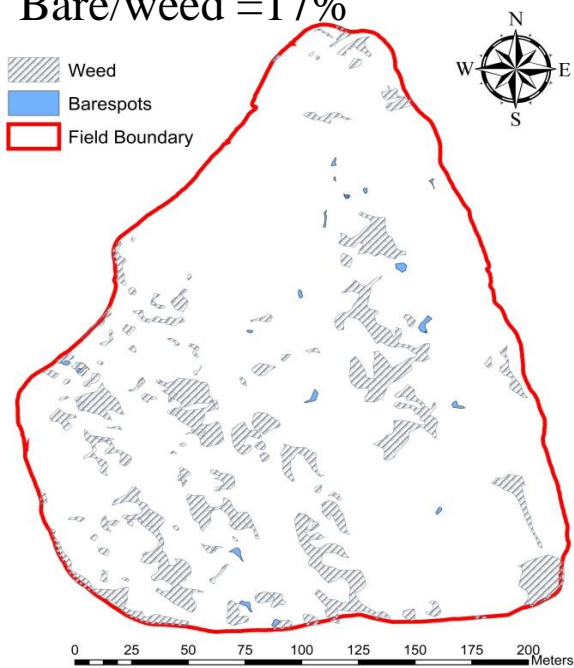
Harvester efficiency at different head heights and comparison with control head height

- Rocks, stumps, sticks and debris
- slope of the field
- Tall weeds, grasses
- Height of blueberry plants
- Bare patches of the field
- Plants density of blueberry plants
- From bare patch to blueberry plant zone and vice versa

➤ On-Line Computer Program for Precise Berry Harvesting Recommendations

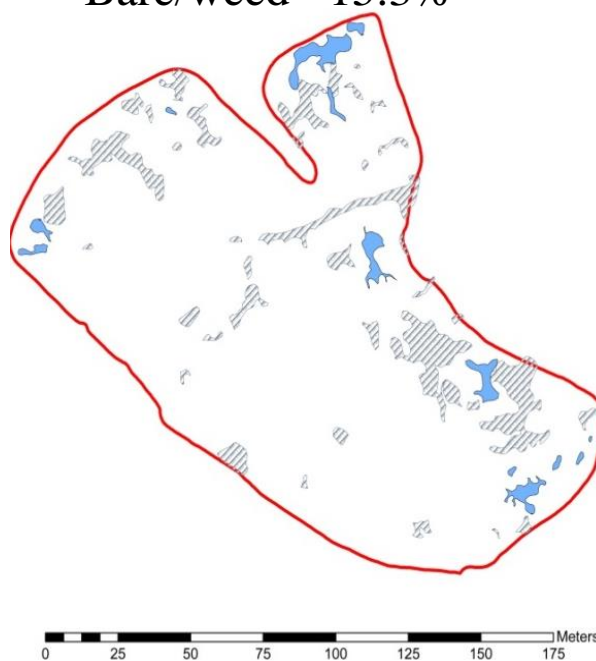
Site Selection

Area = 3.2 ha
Bare/weed = 17%



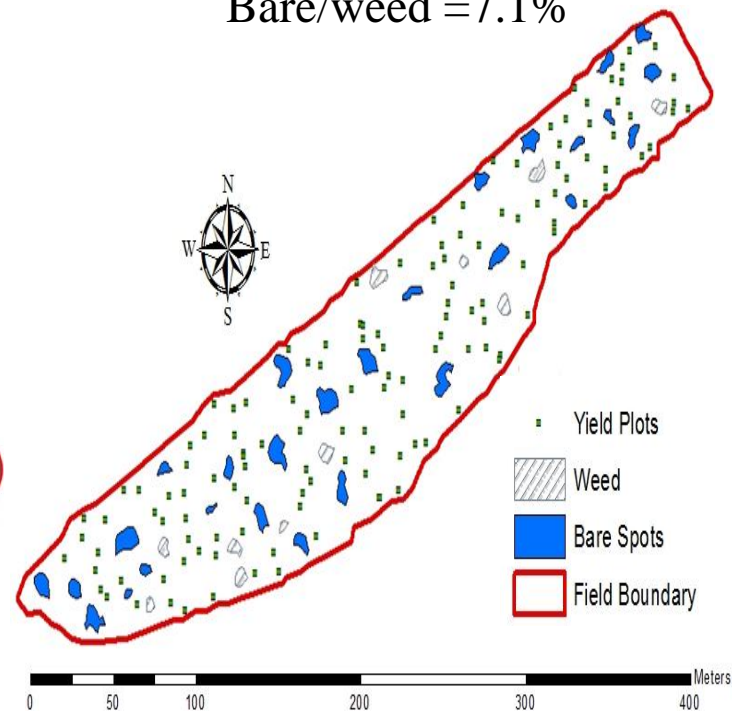
Cooper Site

Area = 1.9 ha
Bare/weed = 15.3%




Small Scott Site

1.6 ha
Bare/weed = 7.1%



Quantification of Losses

Experiment Design Parameters

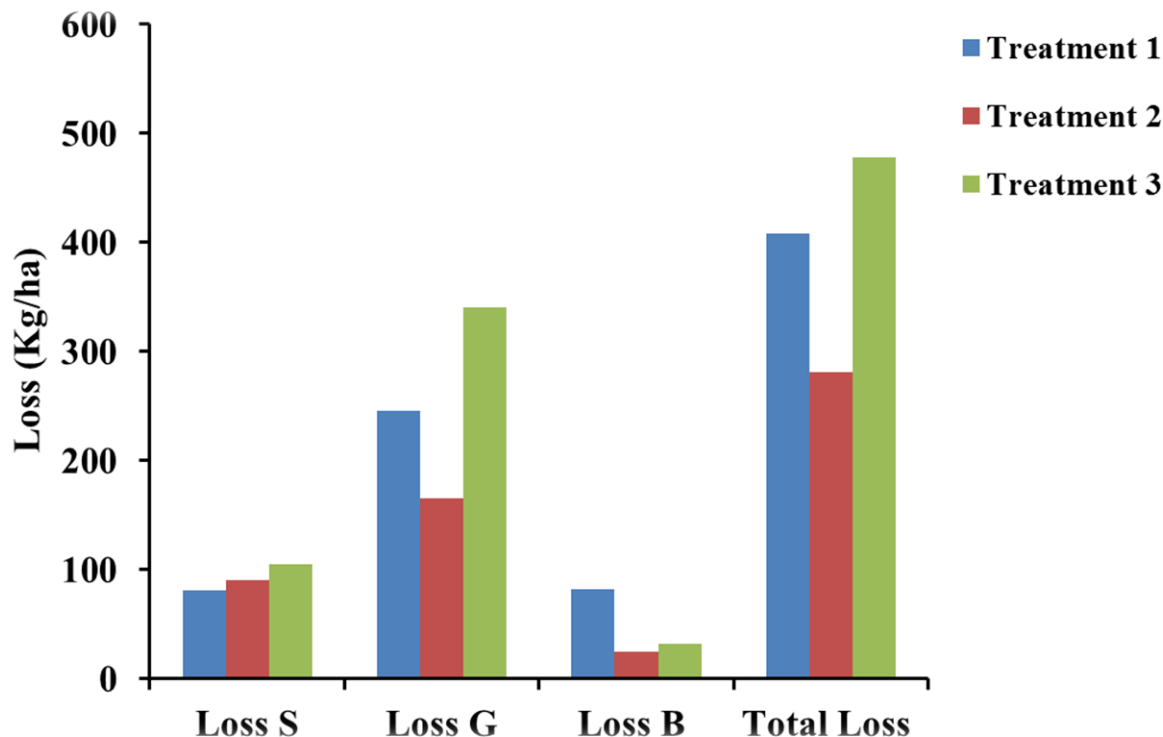
Speed (mile/hr)	Revolutions (rpm)	Sample Collection		
0.75, 1.0, 1.25	26	<input type="text"/>	<input type="text"/>	<input type="text"/>
	26	<input type="text"/>	<input type="text"/>	<input type="text"/>
	26	<input type="text"/>	<input type="text"/>	<input type="text"/>
0.75, 1.0, 1.25	28	<input type="text"/>	<input type="text"/>	<input type="text"/>
	28	<input type="text"/>	<input type="text"/>	<input type="text"/>
	28	<input type="text"/>	<input type="text"/>	<input type="text"/>
0.75, 1.0, 1.25 	30	<input type="text"/>	<input type="text"/>	<input type="text"/>
	30	<input type="text"/>	<input type="text"/>	<input type="text"/>
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Variables/Treatments

Ground Speed: 0.75, 1.0 and 1.25 mph

Header Rotations: 26, 28 and 30 rpm

Quantification of Losses – Cooper site

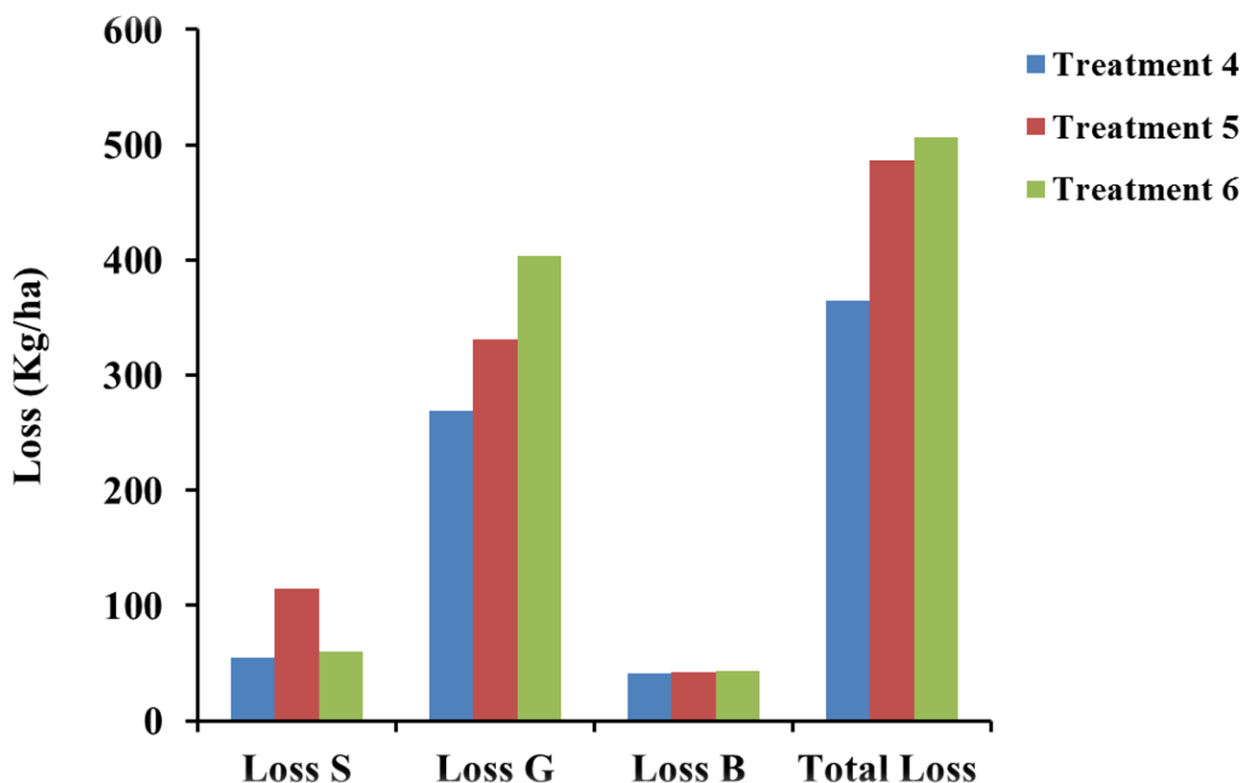


Treatment 1 @ Speed 0.75 mph and 26 rpm

Treatment 2 @ Speed 0.75 mph and 28 rpm

Treatment 3 @ Speed 0.75 mph and 30 rpm

Quantification of Losses – Cooper site

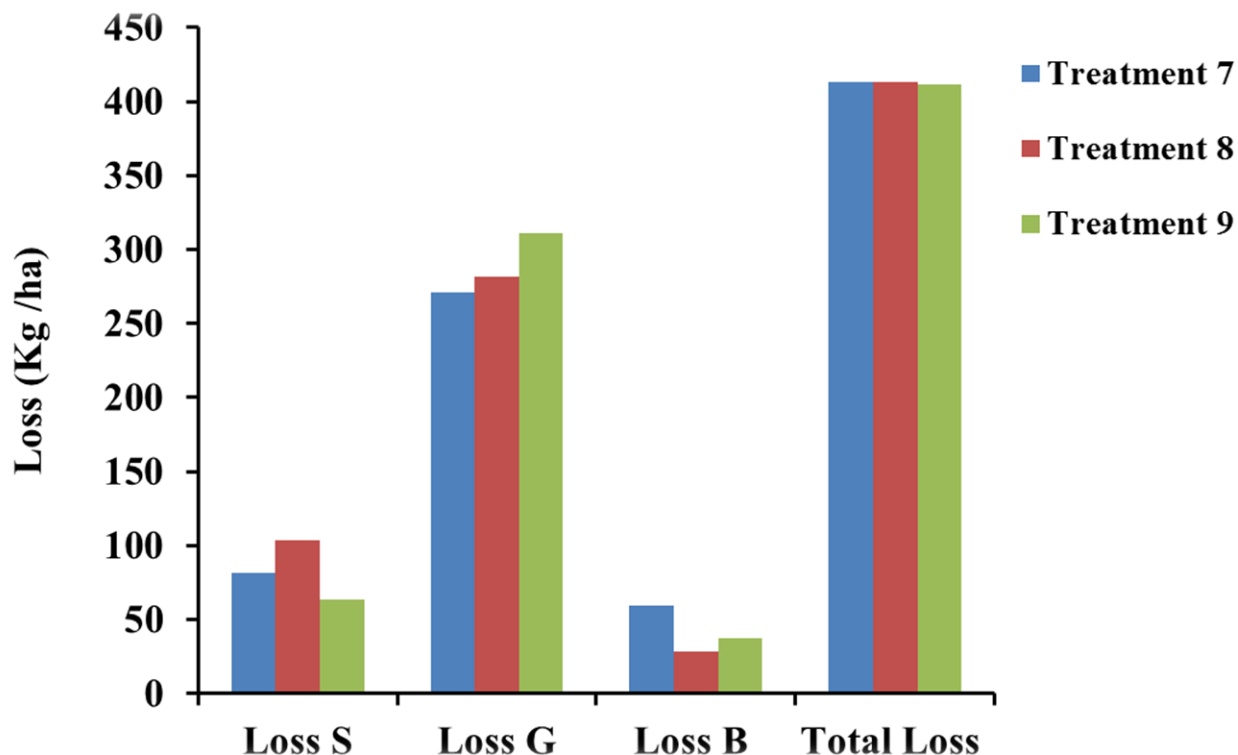


Treatment 4 @ Speed 1.0 mph and 26 rpm

Treatment 5 @ Speed 1.0 mph and 28 rpm

Treatment 6 @ Speed 1.0 mph and 30 rpm

Quantification of Losses – Cooper site



Treatment 7 @ Speed 1.25 mph and 26 rpm

Treatment 8 @ Speed 1.25 mph and 28 rpm

Treatment 9 @ Speed 1.25 mph and 30 rpm

Quantification of Losses – Cooper Site

Trt. 1: 0.75 mph and 26 rpm

Trt. 2: 0.75 mph and 28 rpm

Trt. 3: 0.75 mph and 30 rpm

Trt. 4: 1.0 mph and 26 rpm

Trt. 5: 1.0 mph and 28 rpm

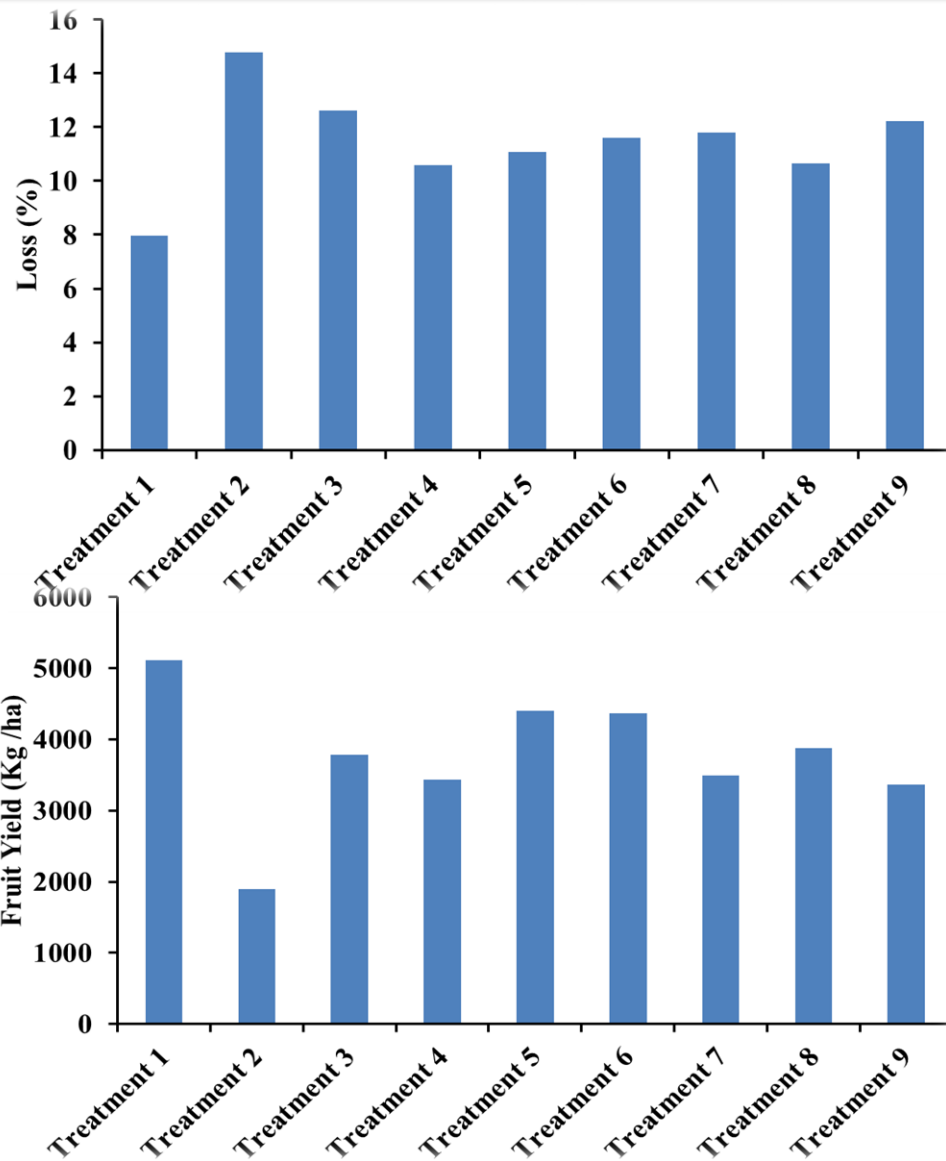
Trt. 6: 1.0 mph and 30 rpm

Trt. 7: 1.25 mph and 26 rpm

Trt. 8: 1.25 mph and 28 rpm

Trt. 9: 1.25 mph and 30 rpm

Fruit Yield: 3700 (kg/ha)



Quantification of Losses – Small Scott

Trt. 1: **0.75 mph and 26 rpm**

Trt. 2: **0.75 mph and 28 rpm**

Trt. 3: **0.75 mph and 30 rpm**

Trt. 4: **1.0 mph and 26 rpm**

Trt. 5: **1.0 mph and 28 rpm**

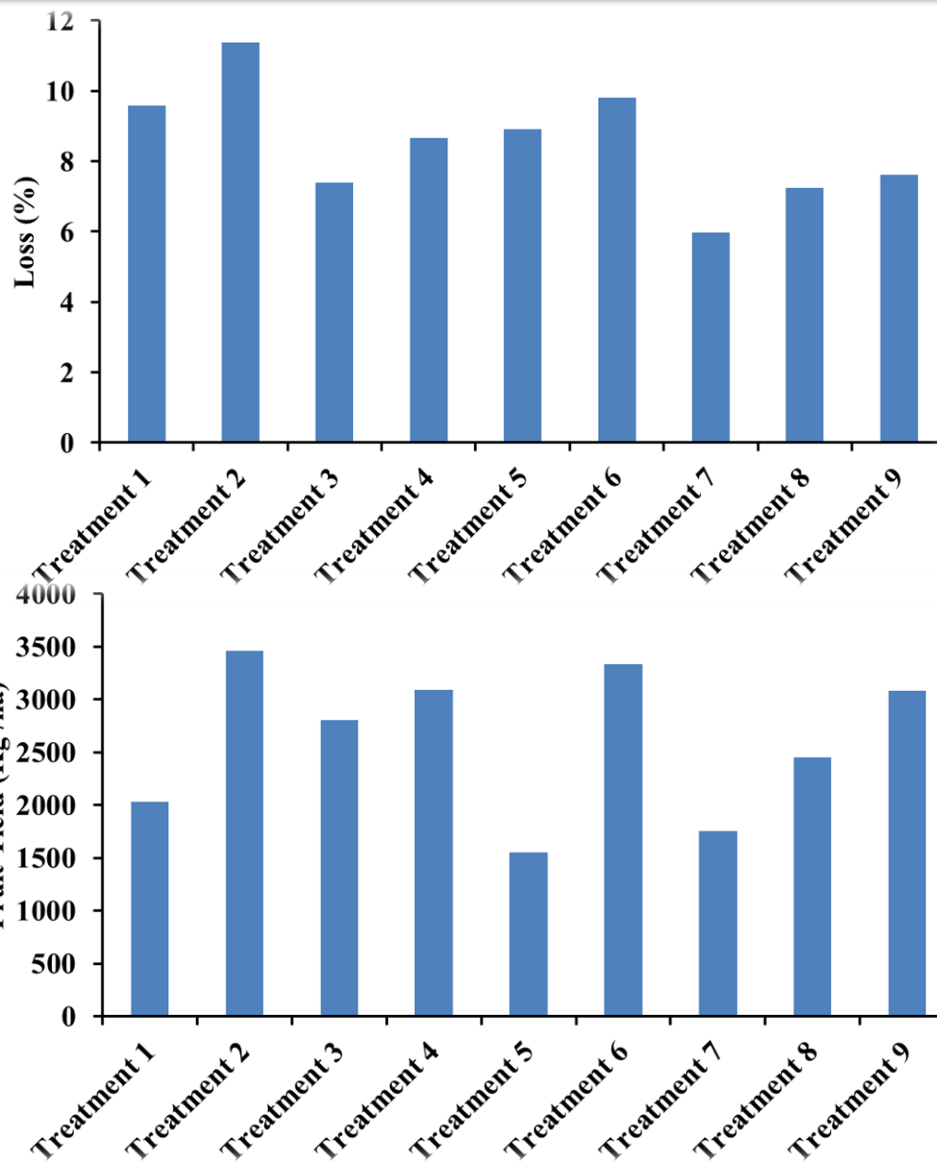
Trt. 6: **1.0 mph and 30 rpm**

Trt. 7: **1.25 mph and 26 rpm**

Trt. 8: **1.25 mph and 28 rpm**

Trt. 9: **1.25 mph and 30 rpm**

Fruit Yield: 2600 Kg/ha



Quantification of Losses – Tracdie site

Trt. 1: 0.75 mph and 26 rpm

Trt. 2: 0.75 mph and 28 rpm

Trt. 3: 0.75 mph and 30 rpm

Trt. 4: 1.0 mph and 26 rpm

Trt. 5: 1.0 mph and 28 rpm

Trt. 6: 1.0 mph and 30 rpm

Trt. 7: 1.25 mph and 26 rpm

Trt. 8: 1.25 mph and 28 rpm

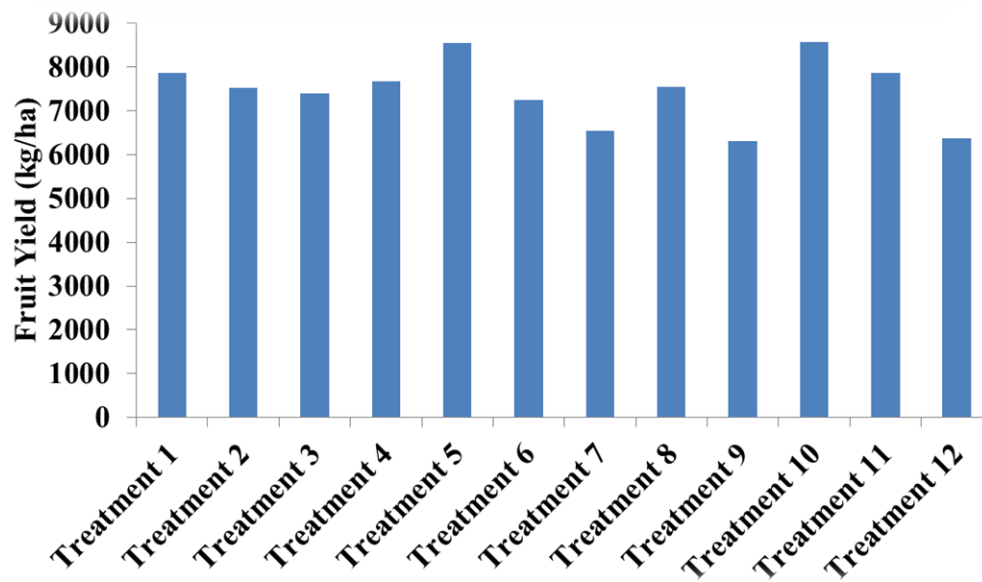
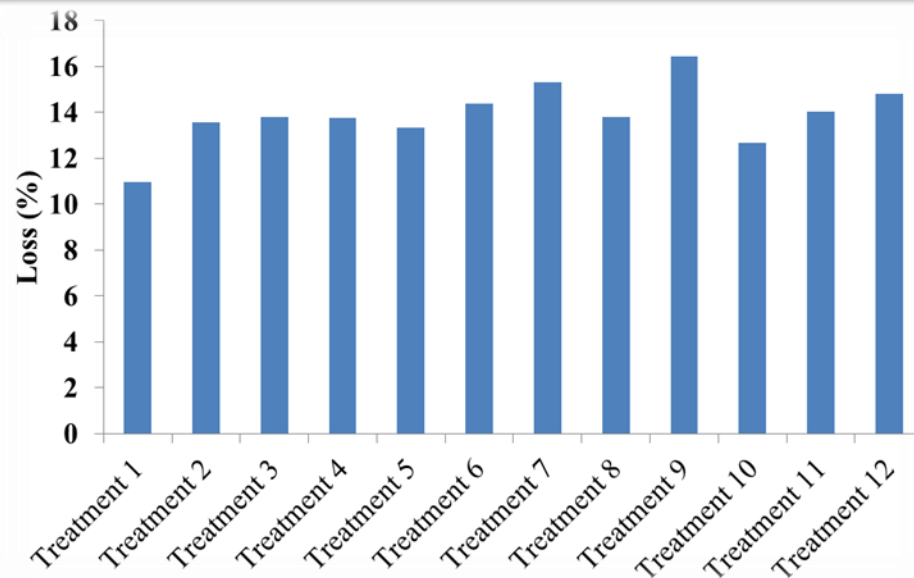
Trt. 9: 1.25 mph and 30 rpm

Trt. 10: 0.6 mph and 18 rpm

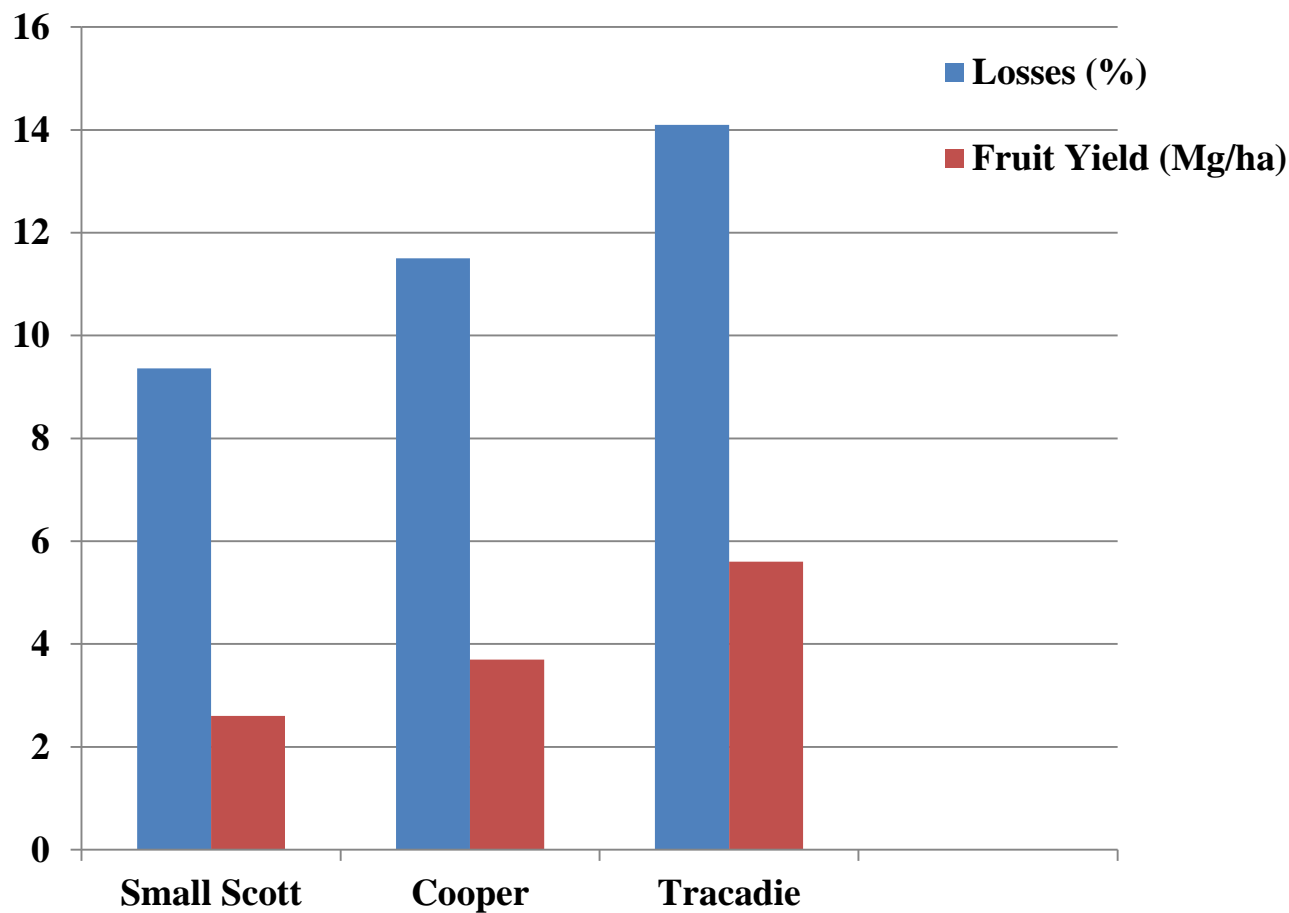
Trt. 11: 0.6 mph and 20 rpm

Trt. 12: 0.6 mph and 22 rpm

Fruit Yield: 5500 Kg/ha



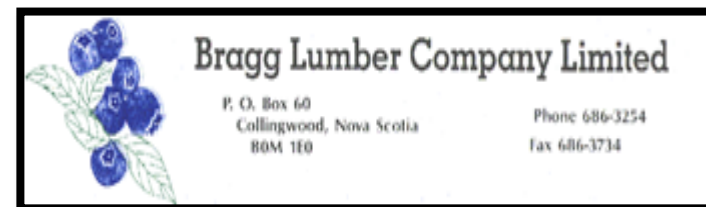
Overall Losses



Outcome and Future Research

- Sensor fusion system (hardware and custom software) was efficient to provide pre-harvest fruit yield to identify overall loss.
- Mapping of wild blueberry fruit yield, plant height, and topographic features will be valuable to develop relationships and will serve as input for modeling.
- Results showed that a treatment combination of 0.75 mph^{-1} and 26 rpm can result in significantly lower losses in wild blueberry fields with yield over 3000 kg ha^{-1} .
- Develop integrated harvesting system using bio-modeling and precision agriculture technologies to improve berry picking efficiency and fruit quality.

ACKNOWLEDGEMENTS



Precision Agriculture Research Team

Questions

