



# Electric Bike Conversion

## Background

Light-duty vehicles were responsible for about half of the GHG emissions in the transport sector.<sup>1</sup>

Our aim is to create an electric bike conversion kit which can be retrofitted to any standard bicycle in hopes to replace light-duty vehicles.

This will provide uphill pedal assistance<sup>2</sup>, downhill speed control, and regeneration of energy through motor braking.

Our system will enable more people to use an environmentally friendly and more energy efficient mode of transportation.

## Design Objectives

- Design a MOSFET bridge circuit as a 3 phase power inverter amplifier to convert DC battery current into 3 phased AC for the motor
- Design a motor control software to produce Pulse Width Modulated signals used to drive the MOSFET bridge (increasing duty cycle increases power delivered)
- Design regenerative braking software that reverses the motor polarity allowing it to act as a generator

## Software Architecture

### Setup Module:

- Sets the data direction for the pins as well as enabling them for reading or writing.
- Enables timers and interrupt service routines
- Initializes analog to digital conversion used to set PWM duty cycle

### Get Hall State Module:

- Outputs the hall state read from the Brushless motor hall sensor signal to find current speed and rotor position

### Brushless DC Move/Brake Module:

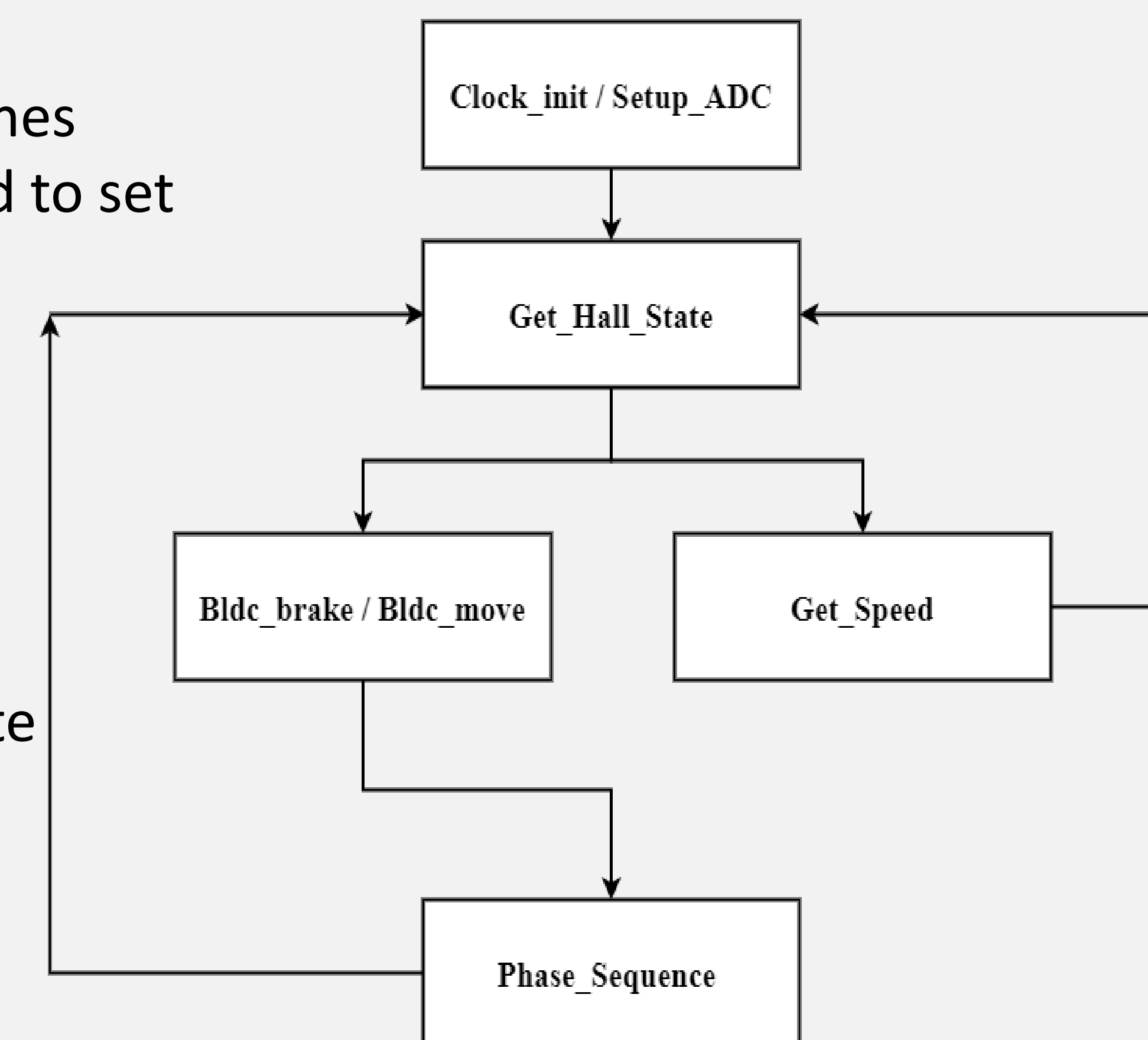
- Calls function to set the coil excitation state of the motor based on the hall state read

### Get Speed Module:

- Calculates and displays current speed

### Phase Sequence Module:

- Sets the phase of the motor



## Hardware Architecture

### DC-DC Converter:

- Steps 48V to 12V

### Throttle Control:

- Controls speed of the bike

### Brake Control:

- Controls the amount of brake applied

### Arduino UNO:

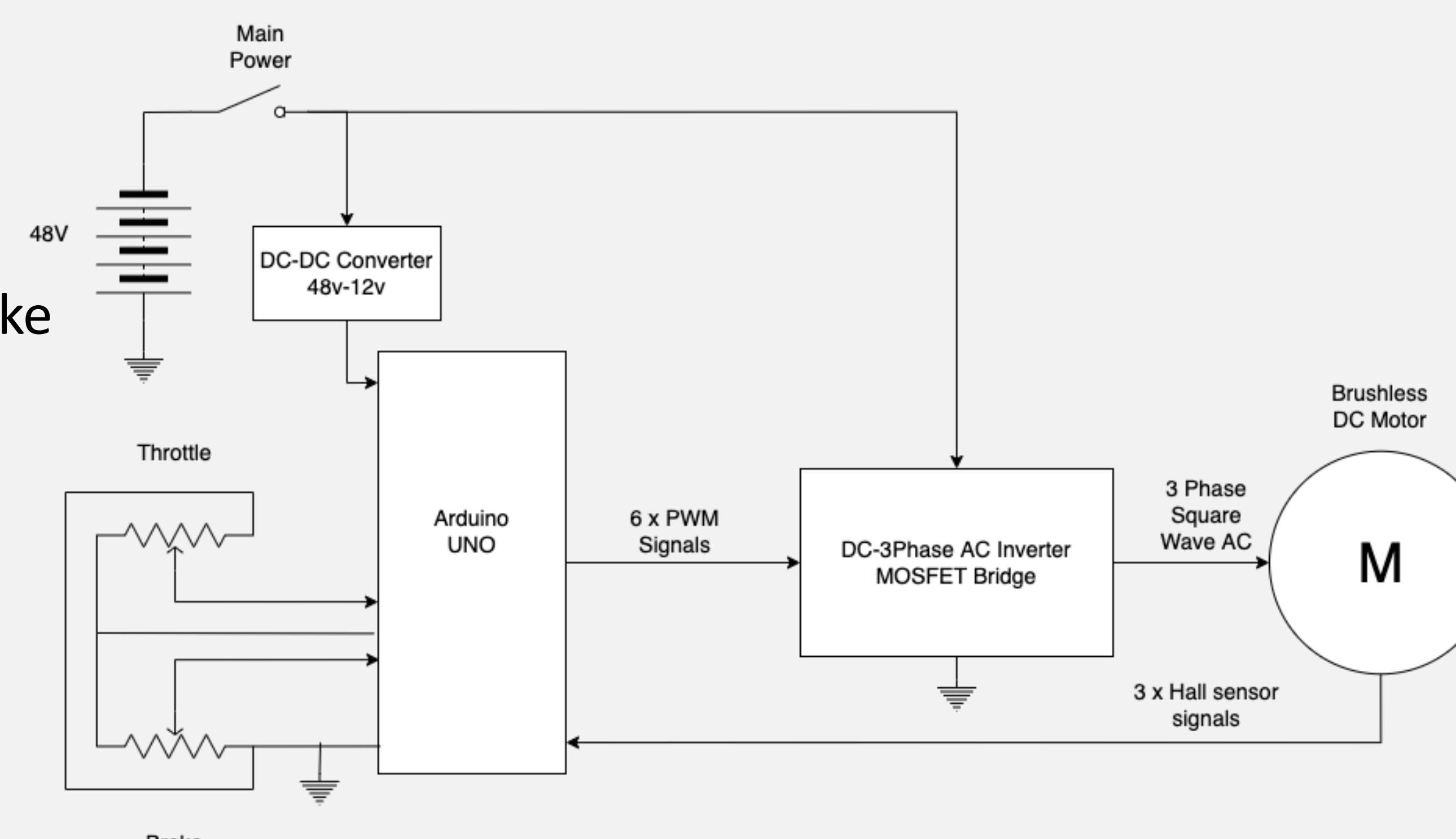
- ATmega328P based microcontroller

### MOSFET Bridge:

- 3 phase power amplifier

### BLDC Motor:

- Prime mover for the bike



## Results

- Created a MOSFET bridge which successfully functioned as a 3 phase amplifier in the system
- Created motor control code which successfully controls the motor
- Successfully implemented regenerative braking by reversing motor polarity in the software
- Output speed reading for use in future user interface

## Future Work

- Develop a test to precisely measure amount of power regenerated by brakes
- Create a PID control to implement cruise control
- Design and implement custom hardware components such as throttle and brake
- Find an LED screen for user interface and implement it with software

## References

- [1] M. Bubbers, "How much do cars really pollute?," The Globe and Mail, 2 August 2019. [Online]. Available: <https://www.theglobeandmail.com/drive/mobility/article-how-much-do-cars-really-pollute/>
- [2] Jamie, "8 Benefits of Using Electric Bikes," [Online]. Available: <https://www.skipeak.net/blog/8-benefits-of-using-electric-bikes>